

Substitute for form 1449A/PTO		Complete if Known		
INFORMATION DISCLOSURE STATEMENT BY APPLICANT (use as many sheets as necessary)		Application Number	10/817,432	
		Filing Date	April 5, 2004	
		First Named Inventor	Michael Hermann	
		Art Unit	2856	
		Confirmation No.	1286	
Sheet		of	Attorney Docket Number	741124-101

U.S. PATENT DOCUMENTS					
Examiner Initials [*]	Cite No. ¹	U.S. Patent Document	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
		Number - Kind Code ² (if known)			
Acc		4,886,364	12/12/1989	Ljung	
		4,477,188	10/16/1984	Stiles et al.	
		4,179,818	12/25/1979	Craig	
		4,825,716	05/02/1989	Roberts et al.	

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Examiner Initials [*]	Cite No. ¹	Foreign Patent Document	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear	T ³
		Country Code ² Number ⁴ Kind Code ⁵ (if known)				
Acc		DE 199 47 292	11/02/2000			
		DE 42 31 935	04/07/1994			
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		EP 0 822 391 A2	02/04/1998	Graham J. Martin		Full
		EP 0 822 391 A3	02/04/1998	Graham J. Martin		Full

OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS			
Examiner Initials [*]	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²

Examiner Signature		Date Considered	8/24/05
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*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

¹ Applicant's unique citation designation number (optional). ² See Kinds Codes of USPTO Patent Documents at www.uspto.gov or MPEP 901.04. ³ Enter Office that issued the document, by the two-letter code (WIPO Standard ST.3). ⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document. ⁵ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST.16 if possible. ⁶ Applicant is to place a check mark here if English language Translation is attached.

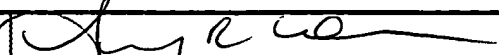
¹ Applicant's unique citation designation number (optional). ² Applicant is to place a check mark here if English language Translation is attached.

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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (use as many sheets as necessary)				Application Number	New Application
				Filing Date	April 5, 2004
				First Named Inventor	Michael HERMANN
				Art Unit	Unknown
				Examiner Name	Unknown
Sheet	1	of	1	Attorney Docket Number	741124-101

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		Number - Kind Code ² (if known)			
AKC		US-5,719,764	02-17-1998	McClary	
		US-6,195,615	02-27-2001	Lysen	
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Examiner Initials ¹	Cite No. ¹	Foreign Patent Document	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear	T ⁴
		Country Code ³ Number ⁴ Kind Code ² (if known)				
AKC		DE 100 60 974 A1	08-30-2001	Albrecht et al.		
		DE 42 05 879 A1	09-02-1993	Pickhard et al.		AB
		DE 195 46 405 A1	06-19-1997	Lysen		AB
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		DE 198 30 359 A1	01-20-2000	Zwosta		AB
		DE 199 49 834 A1	04-19-2001	Lysen		AB

OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS			
Examiner Initials ¹	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
AKC		Lekskulchai PONGSAK et al. ATTITUDE ESTIMATION BY COMPENSATING GRAVITY DIRECTION, DEPARTMENT OF MECHANO-INFORMATICS, THE UNIVERSITY OF TOKYO	
AKC		PROCEEDINGS OF THE 1993 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS, YOKOHAMA, JAPAN, JULY 26-30, 1993, AN INERTIAL NAVIGATION SYSTEM FOR A MOBILE ROBOT, BILLUR BARSHAN AND HUGH F. DURRANT-THYTE, ROBOTICS RESEARCH GROUP, DEPT. OF ENGINEERING SCIENCE, UNIVERSITY OF OXFORD, PAGES 2243-2248	

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